Operating Instructions
MAGSTOP Traffic Barrier
MIB 20/30/40
MLC Controller Unit

Version 2003_05
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1.0 Safety

1.1 Safety symbols used in this handbook

The following symbols are used in this operating instruction to indicate potential risks and other safety information.

Warning!
This symbol is used in this manual to warn installer for potential harm. Please read these instructions very carefully.

Caution!
This symbol is used in this manual to designate those actions or states which represent a potential hazard to property and equipment. Please read these instructions very carefully.

Note!
This symbol is used in this manual to designate useful information for the operator.
1.2 General safety information
This MAGSTOP barrier system has been designed, built and tested using state-of-the-art technology and left our factory only after passing stringent safety and reliability criteria. Nevertheless the barrier system can represent a risk to persons and property if it is not installed and operated correctly. These operating instructions must therefore be read in their entirety and all safety information contained therein must be complied with. The manufacturer shall refuse to accept liability and shall withdraw warranty if this barrier system is used incorrectly or is used for a purpose for which it was not intended.

1.3 Intended use
The MAGSTOP MIB 20/30/40 barriers are designed to control vehicular (see pictogram below) access and exits to car parks, car parking garages, access control applications and highways.
The MAGTRONIC control units have been specially designed for controlling Magnetic barriers.
Any other use of these barrier systems is not permitted.
Modifications or changes to the barrier or to the control modules are prohibited.
Only original Magnetic spare parts and accessories shall be used.

1.4 Warning and safety signage
The Magnetic Automation Corp. MIB barriers come with two (2) safety warning labels (see Figure 1 above) that must be applied to the barrier housing so it can easily be seen when a pedestrian, bicycle users, or motorized vehicle uses the lane. Magnetic Automation Corp. requires that you use universally identifiable pictograms in all entrance/exit lanes, roadways, post, and walls. It is strongly recommended to paint a “NO PEDESTRIAN” pictogram on the roadway immediately adjacent to the parking barrier gate. The barrier arms come already with the safety labels (see Figure 2 above). Removing those safety labels voids any manufacturer’s liability.

Figure 1

Figure 2
1.5 Safety Requirements

- Use vibrant colors on parking equipment
- Always provide proper signage, both on the road way and on other equipment
- Maintain manufacturers warning stickers on gate housing and gate arms.
- Always require that sidewalks are parallel to entrance and exit lanes, or require having pedestrian entrances on opposite side of vehicle entrance and exit.

1.6 Operational safety

A safe clearance distance of at least 2 ft (24 inch) must be provided between the tip of the barrier boom and the closest solid obstacle (building, wall, fence etc.).

Any activity in the entrance and exit lanes should be monitored to ensure a safe operation when opening or closing the barrier gates or to prevent altering or vandalism to the equipment from unauthorized persons.

The motion of the barrier boom must be directly observable by the person operating the barrier.

While the barrier boom is in motion no pedestrian and no vehicle shall be in the immediate vicinity of the barrier.

The assembly and installation instructions must be complied with in their entirety. Any alterations must have received prior confirmation from Magnetic Automation Corp. Barrier booms longer than 14 ft require either a pendulum support or a supporting pillar.

Only certified and trained electrical technicians may perform any electrical connections, wiring work or exchange of components.

Before installing or maintaining the equipment the main power must be disconnected.
1.7 Technical developments
The manufacturer reserves the right to modify, without prior notice, the technical specifications in order to accommodate the latest technical developments. Magnetic Automation Corp. will provide information on the status of existing operating instructions and on any alterations and extensions that may be relevant.

1.8 Warranty
Magnetic provides a limited warranty on its barriers that covers all mechanical and electrical components, but excludes parts subject to wear and tear, for a period of two years from the date of first use or for a maximum of three years from the date on which the system was delivered provided that the operating instructions have been complied with, no unauthorized servicing of machine components has taken place, and that no mechanical damage to the machines is evident.
Please refer to our Warranty Statement.

NOTE: NONE COMPLYANCE WITH THE ABOVE SAFETY REQUIREMENTS (all of Chapter 1) SHALL VOID ANY MANUFACTURERS LIABILITY!
2.0 Installation

2.1 Guidelines for Foundation

To ensure that the equipment is solidly bolted to the ground under all operation conditions, a foundation with the following dimensions shall be provided:

Depth of foundation: at least 3ft (frost-depth)
Base area of foundation: 19" x 23 ½"

The base of the foundation is 4” wider towards the vehicle passage side, than in other section of the foundation (see Fig. S0225).

![Fig. S0225 View of the foundation](image)

1. Anchor bolts (4x)
2. Empty conduit for induction loop lead wire, dia. ½”
3. Conduit for power cables, dia. 1”
4. Conduit for control cables, dia. ½”
5. Concrete foundation
Conduit pipes (with different diameters for low and high voltage cables as per Electrical code) must be installed to run the mains supply cable, the control cables and the induction loop lead wires. A reinforcing steel cage is absolutely essential for the stability of the foundation (see Fig. S0102).

The foundation shall be constructed with at least 2500 PSI grade concrete. The mounting surface must be leveled to insure a solid base for the barrier gate. Once the concrete has set to an adequate hardness, the holes for the anchor bolts can be drilled using the dimensions shown in Fig. S0111 as a guide. Magnetic Automation Corp. recommends using ∅ 3/8” anchor bolts. Please refer to the anchor bolt manufacturers installation requirements.

2.1 Mounting the housing to the ground
To mount the barrier gate on the concrete surface, follow the instructions below.
1. Carefully remove the gate from its shipping crate.
2. Open the barrier door
3. Place the gate on the desired position on the curb but leave 6”-12” distance from the front of the housing to the curb line.
4. Place the gate so that the gate arm flange faces the opposite direction of traffic. Please refer to the figure S0112 and compare the Packing list to assure the correct flange position (example: MIB30R-C100 = RH, MIB30L-C100 = LH).
5. Using a marker, follow the outside and inside contours to the concrete.
6. Remove barrier gate.
7. Using a pencil, mark the location of the mounting holes on the concrete. (See fig. S0111 for dimensions).

8. Drill all four mounting holes and insert the bolts. (Please refer to anchor bolt manufacturers installation specifications). Make sure that the bolts stand up at least 2 inches above the concrete surface.
9. Place the gate on top of the previous marked area.
10. Using the supplied U-channel (in accessory box) secure the gate to the concrete (see Fig. S0106).
11. Attach the field wiring to the proper terminals at the main power board. See Drawing S0113 below. Make certain that the main circuit breaker is switched OFF. Connect all electrical wiring exactly as directed in the Connection Diagram.
12. Secure the boom flange (in accessory box) to the drive shaft using the two M10 mm x 25mm hexagon socket screws. See Drawing below.
13. Attach the boom arm to the flange using the boom attachment kit (in accessory box). Please refer to drawing below.

**Notice:**
With all MIB30 barriers 8mm Nylon hex nuts are provided to mount the boom arm to the flange. This break away feature is only available for boom arms up to 12 ft. For barrier arm length exceeding 12 ft it is not recommended to use any material other then the provided 8mm steel hex nuts. Due to age deterioration (UV radiation), the plastic nuts must be replaced annually.
3.0 Operating the MIB* Barrier Gate

In automatic operation, the MIB* Barrier gate can be operated using the following devices:
- Ticket Spitters
- Vehicle Detectors
- Card Readers
- Coin and Token acceptors
- Radio Controllers
- Switches, Push buttons, and other devices.

4.0 MLC Controller

4.1 General
The MLC control unit (Magnetic Lane Controller) has been specially designed for use with MIB 20/30/40 barrier gates.
All standard configurations can be achieved with this new generation controller.
Via a potentiometer (boom position sensor), located at the motor drive shaft, the position of the barrier arm is continuously detected and the MLC controller evaluates the information.
This replaces the limit switch that is used in conventional barrier control systems. The combination of the potentiometer and the MLC unit guarantees the best possible control of the barrier boom movement.
The controller also has a 16-digit LCD display that shows the current settings and in/out put stages at any time.
Software modifications are normally included at the factory but they can also be loaded very easily into the controller unit at some later date by connecting a software memory card via the interface connector.
The barrier is factory wired and supplied ready for immediate connection.
Operation Instructions

Diagram and text:

- MIB20_30_40 OPERATION MANUAL 2003_05

- Diagram showing various components and connections, with labels such as "boom sensor," "24V external," "inputs," "operating panel," "induction loops," etc.

- Table with specifications for MIB20, MIB30, and MIB40:
  - 230V/50Hz
  - 115V/60Hz
  - Capacitor values: C1, C2, C3, C4, C5, C6

- Legends for diagram:
  - L1: display open/operating panel
  - L2: display close (operating panel)
  - A: loop A
  - B: loop B
  - M: motor connections
  - C0: operating capacitor
  - C1: torque capacitor
  - K1: multifunctional relay 1 (currentless)
  - K2: multifunctional relay 2 (currentless)

- Function notes: (*) function as per-adjusted mode, see operating instructions.
4.1 MLC Controller Setup

1 16-digit liquid crystal display (LCD) for indicating operational and programmed data
2. Rotary selector switch to select operating and setup modes
3. Black button open/scroll/save (operating mode/programming mode)
4. White button close/enter (operating mode/programming mode)
5. Terminal strip – control voltage side
6. Terminal strip – Motor and relay output

NOTE:
THE MLC* CONTROLLER HAS UNIVERSAL MAIN VOLTAGE INPUT (85-V-265V) BUT THE MOTOR DOESN'T. PLEASE CHECK THE SERIAL NUMBER LABEL FOR THE BARRIER FOR INPUT VOLTAGE.
4.2 Display information

Normal operating mode, rotary switch set to ‘0’. Following information is displayed:

Note:
IN5 (external safety input) must be made (activated) in order for the barrier gate to operate. Standard factory setup is a jumper wire to activate this input and using the internal Loop A as safety device.

Abb. S0228
Display information
4.3 Programming and reading the operating data

General operating data:
Rotary Switch Position 0: Barrier operating mode
Rotary Switch Position 1: program number ................. 1 - 8
Rotary Switch Position 2: torque time ......................... 1 - 30 sec.
Rotary Switch Position 3: barrier-open period ............. 1 - 255 sec.
Rotary Switch Position 4: Sensitivity induction loop A .... 0 - 9 (0=min., 9=max.)
Rotary Switch Position 5: Sensitivity induction loop B .... 0 - 9 (0=min., 9=max.)
Position 6: detector mode A ................................... 0 - 9 (see table for function description)
Position 7: detector mode B ................................. 0 - 8 (see table for function description)
Position 8: frequency of induction loops A/B .............. 10,000 Hz - 90,000 Hz
Position 9: spare
Position A: spare
Position B: spare
Position C: spare
Position D: hardware error controller ..................... hexadecimal error code
Position E: language ......................................... German, English, French, Spanish
Position F: factory settings .................................. resets all operating data to default settings
4.3.1.1 Programming modes short description
(Selector switch position ‘1’ see chapter 5.0 for detailed description):

<table>
<thead>
<tr>
<th>Program number</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Barrier controlled by a potential-free switch</td>
</tr>
<tr>
<td>2</td>
<td>Dead man function</td>
</tr>
<tr>
<td>3</td>
<td>Barrier controlled by pulses from a single push button</td>
</tr>
<tr>
<td>4</td>
<td>Barrier controlled by pulses from two separate push buttons</td>
</tr>
<tr>
<td>5</td>
<td>Automatic with barrier-hold open timer</td>
</tr>
<tr>
<td>6</td>
<td>Automatic with barrier-hold open timer, opening loop disabled when vehicle passes from opposite direction</td>
</tr>
<tr>
<td>7</td>
<td>Automatic without barrier-hold open timer</td>
</tr>
<tr>
<td>8</td>
<td>Automatic without barrier-hold open timer, opening loop disabled when vehicle passes from opposite direction</td>
</tr>
</tbody>
</table>

4.3.1.2 Short description of the general operating data:

<table>
<thead>
<tr>
<th>Torque time: Pos.2</th>
<th>Period for which the barrier motor has full torque, when time expires controller switches to low power consumption.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Barrier-hold open timer Pos.3:</td>
<td>Time after which the barrier closes automatically if no vehicle has passed through the safety device.</td>
</tr>
<tr>
<td>Loop sensitivity</td>
<td>Inductive loop Sensitivity level A = safety/closing loop, B = opening / presence loop</td>
</tr>
<tr>
<td>Loop A Pos. 4</td>
<td></td>
</tr>
<tr>
<td>Loop B Pos. 5</td>
<td></td>
</tr>
<tr>
<td>Detector mode</td>
<td>Function of the loop detectors A/B and the relays K1/K2. See Section 6.5: ‘Adjusting the induction loops’.</td>
</tr>
<tr>
<td>Loop A Pos. 6</td>
<td></td>
</tr>
<tr>
<td>Loop B Pos. 7</td>
<td></td>
</tr>
</tbody>
</table>
| Detector frequency Pos. 8 | Displays current frequency for loop A and loop B  
See Chapter 9.0 for more details. |
| K1 relay output Pos. B | This setting is only functioning when Mode Loop a = 0 (disabled). The position when Relay K1 should switch can be adjusted. |
| Hardware error Pos. D | Hexadecimal error code, only relevant for manufacturer’s own error detection procedures |
| Language Pos. E   | Language selection for LCD messages (German, English, French, Spanish) |
| Factory settings Pos. F | Resets the operating data to the original default settings. Caution! Use only in exceptional circumstances! |
5.0 Programming Modes

1.0 To select a Programming mode turn the rotary switch in position 1.
Display Message:

```
program number X
```

2.0 To change to different Program Mode press and hold both, the black and the white
button down. A cursor will appear below the number. Release both buttons.
3.0 When cursor appeared below the number use the black button to scroll through
the available program modes.
4.0 When desired mode appeared on display press the white button.

Display Message:

```
Save Y=↑ N=↓ ?
```

5.0 In order to save your changes press the Black button
Display Message:

```
program number X
```

6.0 To return to the normal operating mode turn rotary switch to Position 1
5.1 Available Program Modes and functions

Important note: The information provided here is based on the standard program S24008. Differences may exist to other standard programs or customized versions. These programs are documented and attached to this standard manual as addendum. To find out what software is currently installed please read chapter 17.1. All external equipment that uses the MLC* controller inputs (e.g. push buttons, light barriers, limit switches) must be connected as potential free contacts. Contact Magnetic for advice before connecting any equipment that doesn’t meet those requirements.

Note:
DO NOT CONNECT ANY DEVICE WHICH WOULD DELIVER ANY VOLTAGE OF ANY KIND TO THE INPUTS OF THE MLC* CONTROLLER.

Note:
External safety devices other than the internal loop A of the MLC* controller must be connected as normally closed contact to IN 5 (Terminal 32) and terminal 33 (+24VDC). If the internal loop A is used as safety device no additional wiring is necessary but a jumper wire between IN5 (terminal 32) and terminal 33 (+24VDC) is imperative. This jumper wire comes factory wired and loop A is active as safety device.

Following are the functional descriptions of the available Program Modes
5.1.1 Program 1 (Mode 1):

(Maintained contact)
A potential free switch controls the barrier.
Contact closed = barrier closed.  Contact open = barrier open.

Internal Loop A (safety loop) will not close the gate. Loop B can only operated as presence loop.

Connections:
IN1 Terminal 27 and 28 = no function
IN2 Terminal 27 and 29 = no function
IN3 Terminal 27 and 30 = Contact closed=gate closed, Contact open=gate open.
IN4 Terminal 27 and 31 = no function
IN5 Terminal 31 and 33 = External Safety device (Normally closed contact). The safety device will not close the gate. Loop B can only be operated as presence loop.

Wiring Diagram:

Note:
This program mode is mostly used when only one switch is available and a guard, who is in the vicinity of the barrier, operates the gate.
When using other safety devices then the internal safety Loop A connect it to IN5 on terminal 32 and 33. The external safety device must use a NC contact and the existing jumper wire must be removed. When no external safety device is used, a jumper wire on IN 5 (wired ex factory) is necessary to operate the gate.
All inputs must be potential free (dry contacts) contacts.
5.1.2 Program 2 (Mode 2):

Dead-man (Pulse to open, maintain contact to close). The gate closing input must be activated (made) until the arm reaches the full down position.

Internal Loop A (safety loop) or the external safety device (IN5) will not close the gate. Loop B can only operated as presence loop.

Connections:
- IN1 Terminal 27 and 28 = Momentary Signal (pulse) to open the gate.
- IN2 Terminal 27 and 29 = no function
- IN3 Terminal 27 and 30 = Maintained Contact to close the gate
- IN4 Terminal 27 and 31 = no function
- IN5 Terminal 31 and 33 = External Safety device (Normally closed contact).

Wiring Diagram:

Note:
This program mode is mostly used when a guard who is in the vicinity of the barrier guards the entrance or exit.

When using other safety devices then the internal safety Loop A connect it to IN5 on terminal 32 and 33. The external safety device must use a NC contact and the existing jumper wire must be removed. When no external safety device is used a jumper wire on IN 5 (wired ex factory) is necessary to operate the gate.

All inputs must be potential free (dry contacts) contacts.
5.1.3 Program 3 (Mode 3):

Pulse control
Each pulse (input) results in a change of travel direction (up/down) of the barrier arm.
1st pulse: barrier opens, 2nd pulse: barrier closes, 3rd pulse: barrier opens, ... etc.
Internal Loop A (safety loop) or the external safety device (IN5) will not close the gate.
Loop B can only be operated as the presence loop.

Connections:

IN1 Terminal 27 and 28 = Momentary Signal 1st pulse: barrier opens, 2nd pulse: barrier closes, 3rd pulse: barrier opens, ... etc.
IN2 Terminal 27 and 29 = no function
IN3 Terminal 27 and 30 = no function
IN4 Terminal 27 and 31 = no function
IN5 Terminal 31 and 33 = External Safety device (Normally closed contact)

Wiring Diagram:

Note:
This program mode is mostly used when a guard who is in the vicinity of the barrier guards the entrance or exit.
When using other safety devices then the internal safety Loop A connect it to IN5 on terminal 32 and 33. The external safety device must use a NC contact and the existing jumper wire must be removed. When no external safety device is used a jumper wire on IN 5 (wired ex factory) is necessary to operate the gate.
All inputs must be potential free (dry contacts) contacts.
5.1.4 Program 4 (Mode 4):
Pulses from two different normally open devices control the barrier position.
Internal Loop A (safety loop) or the external safety device (IN5) will not close the gate.
Loop B can only operated as presence loop.

Connections:
IN1 Terminal 27 and 28 = Momentary Signal gate open
IN2 Terminal 27 and 29 = Override gate open (highest priority)
IN3 Terminal 27 and 30 = Momentary Signal gate close
IN4 Terminal 27 and 31 = no function
IN5 Terminal 31 and 33 = External Safety device (Normally closed contact)

Wiring Diagram:

Note:
This program mode is used mostly on toll road applications where lane controllers
control the gate and no automatic functioning is required.
When using other safety devices then the internal safety Loop A connect it to IN5 on
terminal 32 and 33. The external safety device must use a NC contact and the existing
jumper wire must be removed. When no external safety device is used a jumper wire on
IN 5 (wired ex factory) is necessary to operate the gate.
Inputs on IN2 will override all existing closing inputs.
All inputs must be potential free (dry contacts) contacts.
5.1.5 Program 5 (Mode 5):

Automatic Mode.
The barrier is opened by a pulse and/or opening loop and closes automatically after an adjustable time, or immediately after the safety device (Loop A or external IN5) has been passed or a closing input on IN3 has been given.

Connections:
IN1 Terminal 27 and 28 = Momentary Signal gate open
IN2 Terminal 27 and 29 = Override gate open (highest priority)
IN3 Terminal 27 and 30 = Momentary Signal gate close
IN4 Terminal 27 and 31 = no function
IN5 Terminal 31 and 33 = External Safety and gate Closing device (Normally closed contact).

Wiring Diagram:

Note:
This program mode is used when automatic functioning of the gate is required. The gate receives an opening command and closes when the vehicle passes through the safety/closing loop after the adjustable hold-open time expires or when a closing input on IN3 was made.
When using other safety devices then the internal safety Loop A connect it to IN5 on terminal 32 and 33. The external safety device must use a NC contact and the existing jumper wire must be removed. When no external safety device is used a jumper wire on IN 5 (wired ex factory) is necessary to operate the gate.
Inputs on IN2 will override all existing closing inputs.
All inputs must be potential free (dry contacts) contacts.
If Loop A is activated and loop B configured as opening loop the gate closes after the vehicle passed both loops, not immediately after leaving the safety loop. Logic: Loop A, AB,B, gate closes. See drawings below.

1.0 Gate closed, patron opens gate.

2.0 Gate opens and vehicle passes through Loop A, gate still in up Position.

3.0 Vehicle leaves Loop B and gate closes.
5.1.6 Program 6 (Mode 6):

This program works essentially the same way as Program 5 but has directional loop logic in addition to the Program 5 features. The difference is that in Program 5 the barrier closes automatically after a vehicle has completely passed over the safety and opening loops. In Program 6, the barrier closes immediately after the vehicle has crossed the safety loop. The opening loop has, at this time, no effect as long the safety-closing loop is triggered first.

Connections:
IN1 Terminal 27 and 28 = Momentary Signal gate open
IN2 Terminal 27 and 29 = Override gate open (highest priority)
IN3 Terminal 27 and 30 = Momentary Signal gate close
IN4 Terminal 27 and 31 = no function
IN5 Terminal 31 and 33 = External Safety and gate Closing device (Normally closed contact.)

Wiring Diagram:

Note:
This program mode is used when automatic functioning of the gate is required. The gate receives an opening command and closes when the vehicle passes through the safety/closing loop after the adjustable hold-open time expires or when a closing input at IN3 was made.
When using other safety devices then the internal safety Loop A connect it to IN5 on terminal 32 and 33. The external safety device must use a NC contact and the existing...
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A jumper wire must be removed. When no external safety device is used a jumper wire on IN 5 (wired ex factory) is necessary to operate the gate.

Inputs on IN2 will override all existing closing inputs.
All inputs must be potential free (dry contacts) contacts
If Loop A is activated and loop B configured as opening loop the gate closes after the vehicle passed Loop A
Logic: Loop A, AB,B gate closes. See drawings below.

1.0 Gate closed, patron opens gate.

![Diagram 1](image)

2.0 Gate opens and vehicle passes through Loop A, gate closes.

![Diagram 2](image)

3.0 Vehicle leaves Loop B and gate remains closed.

![Diagram 3](image)
5.1.7 Program 7 (Mode 7):
Like mode 5 but without automatic time-out to close. The barrier remains open until a vehicle has activated the safety device and only closes after it has left the detection area or a closing command was given.

Connections:
IN1 Terminal 27 and 28 = Momentary Signal gate open
IN2 Terminal 27 and 29 = Override gate open (highest priority)
IN3 Terminal 27 and 30 = Momentary Signal gate close
IN4 Terminal 27 and 31 = no function
IN5 Terminal 31 and 33 = External Safety and gate Closing device (Normally closed contact.)

Wiring Diagram:

Note:
This program mode is used when the gate is used in parking applications where the barrier is controlled by an entry or exit station and no hold-open timer is required. The gate will only close when a vehicle passed through the safety/closing loop or a closing pulse was given (for example: Back out timer).
When using other safety devices then the internal safety Loop A connect it to IN5 on terminal 32 and 33. The external safety device must use a NC contact and the existing jumper wire must be removed. When no external safety device is used a jumper wire on IN 5 (wired ex factory) is necessary to operate the gate.
Inputs on IN2 will override all existing closing inputs.
All inputs must be potential free (dry contacts) contacts.
5.1.8 Program 8 (Mode 8):
Like mode 6 but without automatic time out to close. The barrier remains open until a vehicle has activated the safety device and only closes after it has left the detection area or a closing command was given.

Connections:
IN1 Terminal 27 and 28 = Momentary Signal gate open
IN2 Terminal 27 and 29 = Override gate open (highest priority)
IN3 Terminal 27 and 30 = Momentary Signal gate close
IN4 Terminal 27 and 31 = no function
IN5 Terminal 31 and 33 = External Safety and gate Closing device (Normally closed contact.)

Wiring Diagram:

Note:
This program mode is used when automatic functioning of the gate is required. The gate receives an opening command and closes when the vehicle passes through the safety/closing loop after the adjustable hold-open time expires or when a closing input at IN3 was made.
When using other safety devices then the internal safety Loop A connect it to IN5 on terminal 32 and 33. The external safety device must use a NC contact and the existing jumper wire must be removed. When no external safety device is used a jumper wire on IN 5 (wired ex factory) is necessary to operate the gate.
Inputs on IN2 will override all existing closing inputs.
All inputs must be potential free (dry contacts) contacts.
6.0 Torque time settings

During the arm movement the motor runs with full torque (i.e. 115VAC). After reaching the end positions the MLC controller switches the motor to a low power consumption mode. The time in which the motor runs in full torque can be adjusted using the torque time menu at rotary switch position 2. This can be necessary when the barrier is installed in heavy wind areas or extreme cold climates. Ex factory the torque time is adjusted using the pre-programmed settings of the MLC controller software. The torque time is adjustable from 1-30 seconds.

6.1 How to adjust the torque time:

1.0 To change the torque timer turn the rotary switch to position2.

Display Message:

<table>
<thead>
<tr>
<th>Torque time</th>
<th>XX</th>
</tr>
</thead>
</table>

XX = Current torque time setting

2.0 To change the torque time press and hold the black and the white button down. A cursor will appear below the first number. Release both buttons. To change this number press the black button, to switch to the second number press the white button.

3.0 When desired time is adjusted press the white button.

Display Message:

| Save Y=↑ N=↓ ? |

5.0 In order to save your changes press the Black button

Display Message:

<table>
<thead>
<tr>
<th>Torque time XX</th>
</tr>
</thead>
</table>

XX = Adjusted torque time setting.

6.0 To return to the normal operating mode turn rotary switch to Position 1
7.0 Hold Open timer

The “Hold open timer” is only effective in the automatic Programming modes 5 and 6. The barrier will close when this timer expires after a barrier opening command has been given but no vehicle has passed the safety/closing device within the adjusted time. Ex- 

factory the timer is adjusted to 35 seconds. The timer can be adjusted from 1-255 seconds.

7.1 How to adjust the hold open timer:

1.0 To change the hold open time, turn the rotary switch to position 3.

Display Message:

```
Hold-open t XXX
XX = Current time setting
```

4.0 To change the hold open time press and hold both, the black and the white button down. A cursor will appear below the first number. Release both buttons. To change this number press the black button, to switch to the second or third number press the white button to change the numbers press the black button and the number increments by 1.

5.0 When desired time is adjusted press the white button.

Display Message:

```
Save Y=↑ N=↓ ?
```

5.0 In order to save your changes press the Black button.

Display Message:

```
Hold-open t XXX
XX = Adjusted hold open time.
```

6.0 To return to the normal operating mode turn the rotary switch to Position 1.
8.0 Loop Detector Sensitivity

Each individual internal loop detector has its own sensitivity adjustment. Rotary switch position 4 adjusts the sensitivity for Loop A and position 5 for Loop B. It might be necessary to change the sensitivity of the loop if the loop at the individual installation requires it. Ex factory the loop sensitivity for Loop A and Loop B is adjusted to 5.

The sensitivity can be adjusted from 0-9 with the higher number being the highest sensitivity.

8.1 How to adjust the Loop A sensitivity:

1.0 To change the sensitivity for Loop A turn the rotary switch to position 4.

Display Message:

<table>
<thead>
<tr>
<th>Sensitivity A</th>
<th>X</th>
</tr>
</thead>
</table>

XX = Current sensitivity setting

2.0 To change the sensitivity press and hold both, the black and the white button down. A cursor will appear below the number. Release both buttons. To change the number press the black button, the number increments by 1.

3.0 When the desired number is displayed press the white button.

Display Message:

| Save Y=↑ N=↓ ? |

4.0 In order to save your changes press the Black button

Display Message:

<table>
<thead>
<tr>
<th>Sensitivity A</th>
<th>X</th>
</tr>
</thead>
</table>

XX = Adjusted sensitivity setting.

5.0 To return to the normal operating mode turn rotary switch to Position 1.

6.0 To adjust the Loop B sensitivity turn the rotary switch to Position 5 and follow above steps 1-5.
9.0 Configuring the loop detectors

The MLC controller used in all Magnetic MIB Barriers comes standard with two internal loop detectors, Loop A and Loop B. Each loop has one NO & NC relay output available. Both loop detectors and the relay can be configured using the programming menu.

9.1 Safety/Closing Loop A

Loop A (Terminal 39 and 40) is configured ex factory as safety/closing loop. The output relays K1 are located on terminal 16 (Common), 17 (NC) and 18 (NO).

To configure the loop detector and the relay function please follow these steps:

1.0 Turn rotary switch in Position 6

Display Message:

```
Mode Loop A  X
X = Current Program mode number
```

2.0 To change the Loop mode press and hold both, the black and the white button down. A cursor will appear below the number. Release both buttons.

3.0 When cursor appears below the number use the black button to scroll through the available program modes.

4.0 When desired mode appears on the display press the white button

Display Message:

```
Save Y=↑ N=↓ ?
```

5.0 In order to save your changes press the Black button

Display Message:

```
Mode Loop A  X
X = Selected Loop mode number
```

6.0 To return to the normal operating mode turn rotary switch to Position 1
9.2 Loop A Mode function

9.2.1 Detector Mode A

<table>
<thead>
<tr>
<th>Mode</th>
<th>Internal function</th>
<th>Function K1</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Loop is disabled</td>
<td>Maintained contact when gate is full open</td>
</tr>
<tr>
<td>1</td>
<td>Safety / closes barrier (Program 5-8)</td>
<td>Maintained contact when gate is full open</td>
</tr>
<tr>
<td>2</td>
<td>Safety / closes barrier (Program 5-8)</td>
<td>Maintained contact when Loop A is occupied</td>
</tr>
<tr>
<td>3</td>
<td>Safety / closes barrier (Program 5-8)</td>
<td>Pulse signal when vehicle enters Loop A</td>
</tr>
<tr>
<td>4</td>
<td>Safety / closes barrier (Program 5-8)</td>
<td>Pulse signal when vehicle leaves Loop A</td>
</tr>
<tr>
<td>5</td>
<td>Safety / closes barrier (Program 5-8)</td>
<td>Pulse signal with directional logic (see below)</td>
</tr>
<tr>
<td>6</td>
<td>Safety / closes barrier (Program 5-8)</td>
<td>Pulse signal with directional logic (see below)</td>
</tr>
<tr>
<td>7</td>
<td>Safety / closes barrier (Program 5-8)</td>
<td>Maintained Signal with directional logic (see below)</td>
</tr>
<tr>
<td>8</td>
<td>Safety / closes barrier (Program 5-8)</td>
<td>Maintained Signal with directional logic (see below)</td>
</tr>
<tr>
<td>9</td>
<td>No safety/closing function</td>
<td>Maintained contact when Loop A is occupied</td>
</tr>
</tbody>
</table>

9.2.2 Directional Logic Loop A

In Loop Modes 5, 6, 7 and 8 the relays corresponding to Loop A and Loop B can be set to provide pulses or maintained contacts depending in what direction the vehicle travels. Relay K1 (Terminal 16/17/18) respond to Loop A.

**Loop A Mode 5**

Vehicle travels from Loop B to Loop A. A 300mS pulse will be issued on relay K1 when vehicle drives on Loop B and then Loop A.

Logic:
B/BA (pulse)

Note:
For the directional logic to function, Loop A and Loop B, it must be assured that the vehicles that use this lane trigger both loops at the same time. If this cannot be achieved a special input counting software is required. In that case please call for further details.
Loop A Mode 6

Vehicle travels from Loop B to Loop A. A 300mS pulse will be issued on relay K1 when vehicle drives on Loop B then loop A and then leaves Loop B while still on Loop A.

Logic: B/BA/A (pulse)

Note:
For the directional logic to function, Loop A and Loop B, it must be assured that the vehicles that use this lane trigger both loops at the same time. If this cannot be achieved a special input counting software is required. In that case please call for further details.

Loop A Mode 7

Vehicle travels from Loop B to Loop A. A maintained contact on relay K1 is made when vehicle drives from loop B to loop A until the vehicle leaves loop A.

Logic: B/BA (Maintained contact)/A (Maintained contact)

Note:
For the directional logic to function, Loop A and Loop B, it must be assured that the vehicles that use this lane trigger both loops at the same time. If this cannot be achieved a special input counting software is required. In that case please call for further details.

Loop A Mode 8

Vehicle travels from Loop B to Loop A. A maintained contact on relay K1 is made when the vehicle drives from loop B to loop A and leaves loop B while still on loop A.

Logic: B/BA/A (Maintained contact)

Note:
For the directional logic to function, Loop A and Loop B, it must be assured that the vehicles that use this lane trigger both loops at the same time. If this cannot be achieved a special input counting software is required. In that case please call for further details.
9.3 Opening or Presence Loop B

Loop B (Terminal 41 and 42) is configured ex factory as presence loop.
The output relays K2 are located on terminal 19 (Common), 20 (NC) and 21 (NO).

To configure the loop detector and the relay function please follow these steps:

1.0 Turn rotary switch in Position 7

Display Message:

<table>
<thead>
<tr>
<th>Mode Loop B</th>
<th>X</th>
</tr>
</thead>
</table>

2.0 To change the Loop mode press and hold both, the black and the white button down. A cursor will appear below the number. Release both buttons.

3.0 When cursor appears below the number, use the black button to scroll through the available program modes.

4.0 When desired mode appears on display press the white button

Display Message:

| B Presence Loop | B Opening Loop |

5.0 If this installation requires a presence contact (arming loop) select “B Presence Loop” if this installation requires a free entry or exit setup select “B opening loop” by pressing the black button to toggle between the two options. To select the desired option press the white button.

Display Message:

| B Entrance Loop | B Exit Loop |

6.0 The menu now provides the option to select “B Entrance Loop” or “B Exit Loop”. This option effects only software versions with differential counting. Please select if your gate is an exit or an entry lane. If you have traffic in both directions please select “Entrance Loop”. To toggle between the two options press the black button and confirm your selection by pressing the white button.

Display Message:

Save Y=↑ N=↓ ?
7.0 In order to save your changes press the Black button

Display Message:

<table>
<thead>
<tr>
<th>Mode</th>
<th>Internal function</th>
<th>Function K2</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Loop is disabled</td>
<td>Maintained contact when gate is full closed</td>
</tr>
<tr>
<td>1</td>
<td>Opening Loop (Program 5-8) or presence loop</td>
<td>Maintained contact when gate is full closed</td>
</tr>
<tr>
<td>2</td>
<td>Opening Loop (Program 5-8) or presence loop</td>
<td>Maintained contact when Loop B is occupied</td>
</tr>
<tr>
<td>3</td>
<td>Opening Loop (Program 5-8) or presence loop</td>
<td>Pulse signal when vehicle enters Loop A</td>
</tr>
<tr>
<td>4</td>
<td>Opening Loop (Program 5-8) or presence loop</td>
<td>Pulse signal when vehicle leaves Loop A</td>
</tr>
<tr>
<td>5</td>
<td>Opening Loop (Program 5-8) or presence loop</td>
<td>Pulse signal with directional logic (see below)</td>
</tr>
<tr>
<td>6</td>
<td>Opening Loop (Program 5-8) or presence loop</td>
<td>Pulse signal with directional logic (see below)</td>
</tr>
<tr>
<td>7</td>
<td>Opening Loop (Program 5-8) or presence loop</td>
<td>Maintained Signal with directional logic (see below)</td>
</tr>
<tr>
<td>8</td>
<td>Opening Loop (Program 5-8) or presence loop</td>
<td>Maintained Signal with directional logic (see below)</td>
</tr>
</tbody>
</table>

9.3.2 Directional Logic Loop B
In Loop Modes 5,6,7 and 8 the relays corresponding to Loop A and Loop B can be set to provide pulses or maintained contacts depending in what direction the vehicle travels. Relay K2 (Terminal 19/20/21) correspond to Loop B.
Loop B Mode 5

Vehicle travels from Loop A to Loop B. A 300mS pulse will be issued on relay K2 when vehicle drives from Loop A to Loop B and leaves Loop A.

Logic: A/AB/B (pulse)

Note:
For the directional logic to function, Loop A and Loop B, it must be assured that the vehicles that use this lane trigger both loops at the same time. If this cannot be achieved a special input counting software is required. In that case please call for further details.

Loop B Mode 6

Vehicle travels from Loop A to Loop B. A 300mS pulse will be issued on relay K2 when vehicle drives from Loop A to Loop B while still on Loop A.

Logic: A/AB(pulse)

Note:
For the directional logic to function, Loop A and Loop B, it must be assured that the vehicles that use this lane trigger both loops at the same time. If this cannot be achieved a special input counting software is required. In that case please call for further details.

Loop B Mode 7

Vehicle travels from Loop A to Loop B. A maintained contact on relay K2 is made when the vehicle drives from Loop A to Loop B and leaves Loop A while still on Loop B.

Logic: A/AB/B (Maintained Contact)

Note:
For the directional logic to function, Loop A and Loop B, it must be assured that the vehicles that use this lane trigger both loops at the same time. If this cannot be achieved a special input counting software is required. In that case please call for further details.
Loop B Mode 8

Vehicle travels from Loop A to Loop B.
A maintained contact on relay K2 is made when the vehicle drives from loop A to loop B until leaving loop A
Logic:
A/AB (Maintained contact)/B
(Maintained Contact)

Note:
For the directional logic to function, Loop A and Loop B, it must be assured that the vehicles that use this lane trigger both loops at the same time. If this cannot be achieved a special input counting software is required. In that case please call for further details.

10.0 Loop Frequency

The internal loop detectors are designed using the Multiplex technology. This means that the loops connected to one MLC controller cannot interfere with each other. Only loops connected to other detectors can interfere with the loops connected to another controller. Many factors determine loop frequency, including wire size, wire length, the number of turns, lead length, and insulation.
If multiple barriers are installed in close proximity (within 20 feet) it might be necessary to switch individual MLC controllers to low or high frequency. To determine the necessity of a frequency change the MLC controller displays the current frequency of the installed induction loops. The MLC controller operates at a frequency between 10-100khz. The current loop frequency can be viewed by turning the rotary switch in position 8.

10.1 How to view the loop frequency:

1.0 Turn the rotary switch to position 8.
Display message:

**Detector A XXXXX**  \[X = \text{Current Loop frequency}\]

2.0 To toggle between Loop A and Loop B press the white button.
3.0 To return to the normal operating mode turn rotary switch to Position 1

Note:
If Loop A or Loop B is not activated the display shows “OFF”.
The same message appears if the loop frequency is outside the operating limits (10-100khz), not connected properly or when the loop wires are broken.
The frequency display can be used to determine what might be the cause of loop cross talking and can also be used to prevent it from happening. The frequencies of two loops that use different detectors (not connected to the same MLC controller) must be at least 3kHz (3000Hz) apart.

**10.2 How to change the loop frequency:**

The MLC controller has two DIP-switches located below terminal strip numbered 22-42. In order to reach the Dip-switches, remove the terminal strip. Follow the instructions below to remove the terminal strip and change loop frequency.

1.0 Turn the main supply voltage off. There is no need to disconnect any of the control-wiring going to this terminal strip.

2.0 Unscrew the two Phillips head screws located on each end of the terminal strip (see drawing below)

3.0 Pull the terminal strip up and remove it completely from the controller.

4.0 The two dipswitches are located on the right hand side (see drawing) below the loop connector terminals.
5.0 You are now able to change the frequency of each individual loop to “High” or “Low”. See drawing below for settings.

6.0 After changing the DIP-switch settings, replace the terminal strip, secure the Phillips head screws, return the rotary switch to position 0, and turn the main power supply on.

7.0 By moving the rotary switch to position 8 you can view the new frequency settings of your loops.

Note:
Every change in loop frequency requires a controller reset. This can be done by simply turning the power off and turning it back on or pushing both the black and the white button and holding it until the controller resets (approx. 3sec)

11.0 Relay K1 Output

The switching point of relay K1 can be set in relation to the barrier arm position. This can only be done when Loop Mode A is set to “0”. The relay switching point can be set in rotary switch position B.

Follow these steps to change the switch position:

1. Turn the rotary switch to position B

Display Message:

1 - switch on XX

XX = Current switch position setting when barrier goes up.
2. The barrier arm position for when the relay should turn on is shown on the display in degrees. 90 degrees the gate arm is in the full up position, 0 degrees the gate arm is in the full down position. To change the settings press the black and the white button simultaneously. A cursor below the first digit appears. To change the number, press the black button until the desired value appears on the screen (5 degrees increments) To confirm the settings press the white button. This setting will determine when the relay switches on.

Display message:

1 - switch off XX

3. The next display (above) shows the barrier arm position for when relay K1 should turn off again. To change the settings press the black and the white button simultaneously. A cursor below the first digit appears. To change the number, press the black button until the desired value appears on the screen (5 degrees increments) To confirm the settings press the white button. This setting will determine when the relay switches off.

Display message:

Save Y=↑ N=↓ ?

5.0 To save your changes press the Black button
6.0 To return to the normal operating mode turn rotary switch to Position 1
12.0  Error Code
The MLC controller comes with an error display feature that allows the user to determine internal controller errors. This Error is displayed as a hexadecimal code, which can be viewed by turning the rotary switch to position D.
For the field technician only one error code is relevant:

Display message:

**Hardware error 80**

If the above error message is displayed the controller lost its boom sensor position and needs to be readjusted (see chapter 22.1 for readjusting the sensor).

For all other error messages please call Magnetic Automation Corp. for technical support.

13.0  Language Setting
The MLC controller can be set to multiple languages. Following are the pre-programmed standard languages:

- English = English
- Deutsch = German
- Francais = French
- Espanol = Spanish

Move the rotary switch to position E to select the language of your choice.

1.0 Turn the rotary switch to position E
Display Message:

**English**

2.0 To change the language, press both the black and the white button at the same time. A cursor will appear at the last digit to the right.
3.0 Pressing the black button will change the display language.
4.0 To select a new language press the white button
Display message:

**Save Y=↑ N=↓ ?**

5.0 To save your selection, press the black button.
6.0 Return the rotary switch to position 0 for normal operation.
14.0 Default Settings

The controller can be reset to original manufacturer default settings. By doing so all programmed settings are erased. To set the controller to its original manufacturer setting turn the rotary switch to position F.
Press the black and white button, release.
Press the black button to set the controller to default.
15.0 Extended Menu settings:

**Note:**
To access the extended operating menu, the black button must be pressed while the rotary selector switch is turned to the required position.

<table>
<thead>
<tr>
<th>Menu Setting</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Safety Angle: Disabling of safety device in down position Pos. _1</td>
<td>Adjustment of the angle (boom position) at which the safety device (induction loop, light beam etc.) should be disabled before the boom reaches the complete down position.</td>
</tr>
<tr>
<td>Operating hours Pos. _2</td>
<td>Displays the total time in hours the barrier was turned on. Timer is not resetable.</td>
</tr>
<tr>
<td>Operating cycle counter. Pos. _3</td>
<td>Displays the total cycle count of the barrier. This counter is indexed every ten (10) cycles, and is not resetable.</td>
</tr>
<tr>
<td>Brake settings. Pos. _4</td>
<td>This enables you to read the current brake settings, which might be helpful to determine gate failures.</td>
</tr>
<tr>
<td>Not available Pos. _5,6,7,8,A</td>
<td>These positions do not have any function.</td>
</tr>
<tr>
<td>Brake fine tuning Pos. _B</td>
<td>This position allows you to fine tune the brake settings in case the brake might not be satisfactory. Positive numbers: Gate will brake sooner Negative numbers: The gate will brake later.</td>
</tr>
<tr>
<td>Reset Pos. _C</td>
<td>Choice of resetting behavior after the power is restored to the gate. Signal Reset = The gate will reset after the first Input is made. Auto Reset = the gate will reset (close) when power is restored.</td>
</tr>
<tr>
<td>Test Mode Pos. D</td>
<td>This can be used to cycle the gate automatically.</td>
</tr>
<tr>
<td>Motor Pos. E</td>
<td>This menu can be used to adjust the potentiometer.</td>
</tr>
</tbody>
</table>
15.1 Adjusting the safety angle:

This setting allows the user to adjust the boom position in which the controller disables the safety devices. This setting allows the user to increase the safety of the operation or prevent tail gating from happening. To increase safety, the cut off angle is smaller; to prevent tail gating, the cut of angle is higher (i.e. the safety device is disabled sooner). To disable the safety cut off sooner to prevent tailgating will also increase the possibility that vehicles are being hit by the gate arm. This angle is adjustable between 10° - 80° in 5° increments. The down position equals 0° and the complete up position 90°. To change the setting follow steps below.

1.0 Press and hold the black button while turning the rotary switch to position 1

Display Message:

```
Angle safety  XX
X = Current setting
```

2.0 Press the black and the white button simultaneously. A cursor below the first digit appears. To change the number, press the black button. To confirm the settings press the white button.

Display Message:

```
Save Y=↑ N=↓ ?
```

3.0 Press the black button to save the changes.

4.0 Return the rotary switch to position 0 for normal operation.
15.2 Operating hour display:
The total time the controller was turned on can be viewed at rotary position 2. The counter is not resetable.

1.0 Press and hold the black button while turning the rotary switch to position 2.
Display Message:

```
Hours  XXXXX.X
```

X = Current operating hours

2.0 Return the rotary switch to position 0 for normal operation.

15.3 Gate Cycle counter:
This cycle counter displays the gate cycles made with this controller. The counter is not resetable. It indexes every 10 cycles.

To view the counter, follow these steps.

1.0 Press and hold the black button while turning the rotary switch to position 3.
Display Message:

```
Cycles  XXXXX
```

X = Current cycle count

2.0 Return the rotary switch to position 0 for normal operation.
15.4 Reading the Brake Points:
All MIB barriers self adjust to the optimal brake points depending on boom length, boom weight, Barrier model and spring adjustment. The brake points must be within a pre-programmed range. Following table shows the range for each of the barrier models:

<table>
<thead>
<tr>
<th>Barrier Model</th>
<th>Brake Point Up</th>
<th>Brake Point down</th>
</tr>
</thead>
<tbody>
<tr>
<td>MIB20 50Hz</td>
<td>100-220</td>
<td>80-170</td>
</tr>
<tr>
<td>MIB20 60Hz</td>
<td>50-180</td>
<td>70-170</td>
</tr>
<tr>
<td>MIB30 50Hz</td>
<td>40-240</td>
<td>60-280</td>
</tr>
<tr>
<td>MIB30 60Hz</td>
<td>80-290</td>
<td>90-280</td>
</tr>
<tr>
<td>MIB40 50Hz</td>
<td>40-150</td>
<td>60-180</td>
</tr>
<tr>
<td>MIB40 60Hz</td>
<td>70-150</td>
<td>50-200</td>
</tr>
</tbody>
</table>

To view the current brake points follow these steps:

1. Press and hold the black button while turning the rotary switch to position 4. Display Message:

   XXX = Current brake point
   gate position UP
   YYY = Current brake point
   gate position DOWN

2. Return the rotary switch to position 0 for normal operation

Note:
Comparing the displayed brake points with the brake point range of the individual barrier model can determine possible malfunctioning of the barrier.
If the brake points are out of range please follow the instructions in chapter 22.1.

15.5 Resetting the barrier after power failure:
The MLC controller can be set to two different resets after a power failure. Ex factory the setting is “Signal Reset”.

Signal Reset:
If the barrier is in the fully closed position after the power is restored the controller will accept all inputs immediately after booting the software.
If the barrier is not in the fully closed position the gate will open and remain open until the following occurs:
1. Reset by pressing the black and the white button simultaneously for approx 2 sec.
2. Closing input on IN3
3. Passing through the safety/closing device (external or internal).
Before any of the above steps are taken the display will show the following:

![R Reset Requested](image)

The “RESET REQUESTED” display flashes in a 1sec. Interval.

Any of the above actions will reset the controller to the normal operation mode.

The other reset option is

**Auto Reset:**

After the power is restored the barrier reacts to any activated input independent of the barrier arm position. If no opening input is activated and no object is in the safety zone the barrier will close.

Please follow these steps to select the reset mode:

1.0 Press and hold the black button while turning the rotary switch to position C.

Display Message:

![Signal Reset](image)

2.0 Press the black and the white button simultaneously. A cursor appears on the right hand side of the display. To change the setting, press the black button. To confirm the settings press the white button.

Display message:

![Save Y=↑ N=↓ ?](image)

3.0 Press the black button to save the changes.
4.0 Return the rotary switch to position 0 for normal operation.

**15.6 Test Mode**

The MLC controller offers the feature to run the barrier in a test mode without having to install an open close timer or other equipment. During this test mode the barrier will open and close continuously. This can be used for equipment demonstration or testing.

Please follow these steps to set the controller in test mode:

1.0 Press and hold the black button while turning the rotary switch to position D.

Display Message:
2.0 To change to Test Mode press the black and white button simultaneously. Display Message:

![Test Mode](X)

3.0 Release both buttons. The number has now changed to 9, which symbols the test mode is set.

4.0 Return the rotary switch to position 0 Display Message:

![Test Mode](9)

5.0 If no input is activated and no object is in the safety zone the barrier will now start to cycle up and down.

6.0 To return to the normal operation mode, simply turn the rotary switch to position 1 and then back to position 0.
16.0 Installing the Induction Loops

16.1 General induction loop functionality

The Loop detectors operate on the principle of inductance. The detector monitors an insulated electrical wire, placed on or below the road surface (LOOP). Any metallic object, such as a car, which passes through the field will absorb electromagnetic energy and simultaneously decrease the inductance and increase the resonant frequency of the loop. For most conventional installations, when the inductance or frequency changes beyond a preset threshold in the detector electronics, the detector indicates that a vehicle has been detected.

Note:
Only metallic objects can be detected. The loop frequency change depends on the size and form of the to be monitored object (i.e. car) not on the material mass, which does not influence the loop.

The micro controller system self adjusts to the connected loop. Many factors determine loop inductance, including wire size, wire length, the number of turns, lead length, and insulation.

Changes in loop inductance due to temperature or aging are automatically compensated.

Detectors with multiple channels (i.e. dual channel) are monitored using the MULTIPLEX METHOD, which eliminates the interference (cross-talk) between the loops connected to this detector.

16.2 Loop Inductance

16.2.1 Inductance

Inductance is the resistance to the change of current flow. When a current is applied to a conductor (wire) a magnetic field is formed around the conductor (wire). If the current source is removed, the magnetic field collapses into the wire trying to maintain the current flow. By winding several turns of the wire into a coil, the magnetic field is intensified which increases the inductance.

The loop inductance can be measured with an inductivity meter. The unit of measurements is the Henry (h). The inductance depends on the loop perimeter and number of turns. A bigger loop with more turns has a higher Inductance.
16.2.2 Vehicle detection

When a vehicle enters the loop the body and frame provide a conductive path for the magnetic field; causing a loading effect, which in turn causes the loop inductance to decrease. The decreased inductance causes the resonant frequency to increase from the nominal value. If the frequency change exceeds the threshold set by the sensitivity setting, the detector module will output a detect signal.

There has been a misconception that an inductive loop requires a mass of metal for detection. Placing a single wire around the perimeter of the loop and shorting the ends together will quickly disprove the misconception. The single wire forming a shorted turn provides a current path for the magnetic field; thus causing a loading effect similar to that of a vehicle. The shorted turn effect of the single wire coil in the proximity of the loop acts much like a shorted turn secondary of a transformer.

16.2.3 Wire Turns required for loops

The Inductive loop detectors will tune from 70 µH to 500 µH (µH = microHenry). It is preferable that the loop and lead-in have a minimum of approximately 70 µH for stability. The loop inductance should be equal to or greater than the lead-in inductance. If the inductance of the loop exceeds the requirements above, a proper functioning of the detector cannot be guaranteed.

The loop inductance also influences the loop sensitivity. The best results are between 100 and 300 µH.
16.2.4 Loop Inductance calculations

The number of turns required in the loop is dependent on the loop size. The loop inductance can be calculated as follows:

\[ L = \frac{P}{4} (t^2 + t) \]

\( L \) = Inductance (micro Henries)
\( P \) = Perimeter (feet)
\( t \) = Number of turns

The formula can be simplified to: \( L = PK \)
Substituting a constant \( K \) for \((t^2 + t)/4\)
Filling in the Number of Turns and calculating \( K \):

<table>
<thead>
<tr>
<th>Number Of Turns ( t )</th>
<th>( k ) (constant) ( k= (t^2 + t)/4 )</th>
</tr>
</thead>
<tbody>
<tr>
<td>2</td>
<td>1.5</td>
</tr>
<tr>
<td>3</td>
<td>3</td>
</tr>
<tr>
<td>4</td>
<td>5</td>
</tr>
<tr>
<td>5</td>
<td>7.5</td>
</tr>
<tr>
<td>6</td>
<td>11.5</td>
</tr>
<tr>
<td>7</td>
<td>14</td>
</tr>
</tbody>
</table>

Example: 4’ x 8’ with 4 turns
\[ L = PK \]
\[ P = 4’+4’+8’+8’ = 24 \text{ feet} \]
\[ K = 5.0 \]
\[ L = 24 \times 5.0 \]
\[ L = 120 \text{ micro henries} \]

<table>
<thead>
<tr>
<th>PERIMETER FEET</th>
<th>NUMBER OF TURNS</th>
</tr>
</thead>
<tbody>
<tr>
<td>10</td>
<td>2</td>
</tr>
<tr>
<td>20</td>
<td>15</td>
</tr>
<tr>
<td>30</td>
<td>30</td>
</tr>
<tr>
<td>40</td>
<td>45</td>
</tr>
<tr>
<td>50</td>
<td>60</td>
</tr>
<tr>
<td>60</td>
<td>75</td>
</tr>
<tr>
<td>70</td>
<td>90</td>
</tr>
<tr>
<td>80</td>
<td>105</td>
</tr>
<tr>
<td>90</td>
<td>120</td>
</tr>
<tr>
<td>100</td>
<td>135</td>
</tr>
</tbody>
</table>

Note:
Use the highlighted values to determine the number of turns required. ALWAYS USE AT LEAST 2 TURNS. In addition to the above result the inductivity of the wires used in the loop must be added. Depending on the used wire it is between 1 – 1.5 µH per every three (3) feet.
16.3 Loop Detector Sensitivity

The MLC loop detector comes with multiple adjustable sensitivity settings. This means that only vehicles will be detected when the relative frequency change (difference between loop frequency with vehicle and without) is higher than the adjusted sensitivity.

For example:
If the sensitivity of a loop detector is adjusted to 0.05%, only vehicles that change the loop frequency by more than 0.05% will be detected.

Note:
To ensure a failsafe detection of vehicles, the value of the Relative Frequency Change should be at least 10 times higher than the adjusted loop sensitivity.

If the value is lower it might not detect every vehicle (i.e. Pick-Up trucks).
A low Relative Frequency Change value can be caused by wrong loop dimensioning or geometry, not enough windings, not enough clearance to metal objects within the road (i.e. steel reinforcement, sewer grill etc.).

The following table shows the MLC detectors Sensitivity Levels which can be set at rotary switch position 4 for Loop A and 5 for Loop B:

<table>
<thead>
<tr>
<th>Sensitivity level MLC10/11-U100</th>
<th>Sensitivity</th>
</tr>
</thead>
<tbody>
<tr>
<td>9</td>
<td>0.01%</td>
</tr>
<tr>
<td>8</td>
<td>0.015%</td>
</tr>
<tr>
<td>7</td>
<td>0.03%</td>
</tr>
<tr>
<td>6</td>
<td>0.06%</td>
</tr>
<tr>
<td>5</td>
<td>0.09%</td>
</tr>
<tr>
<td>4</td>
<td>0.15%</td>
</tr>
<tr>
<td>3</td>
<td>0.22%</td>
</tr>
<tr>
<td>2</td>
<td>0.3%</td>
</tr>
<tr>
<td>1</td>
<td>0.9%</td>
</tr>
<tr>
<td>0</td>
<td>1.8%</td>
</tr>
</tbody>
</table>

16.4 Installing a Induction Loop

16.4.1 Usage of Pre-manufactured Loops

Any pre-manufactured (formed) loop can be used as long they meet our requirements explained in this manual.
Please refer to loop manufacturers Installation Instructions.
16.4.2 Self-Made Loops

A loop can be manufactured from a single AWG 14-18 stranded XLPE insulated wire rated at 600V. The insulation type XLPE (cross-linked polyethylene) is highly recommended due to its higher quality insulation and higher resistance to abrasion, heat, oil and gasoline. The wire gauge is not important to the operation of the loop detector but the wire should maintain its integrity under the pavement stress. Because asphalt is more flexible than concrete it is recommended that a heavier gauge wire be used for loop installations in asphalt.

The inductance of the loop shall be between 70 and 500 µH, which is usually achieved by having three to five turns in the coil. The loop resistance should be lower than 2 Ω. The loop resistance should be measured after installing the loop but before sealing. The Loop Insulation Resistance must be measured to earth ground. The Insulation Resistance against earth ground must be a minimum of 5 MΩ at 500 Volts. If this is not the case the loop insulation might be damaged. (See chapter 16.2 Loop Inductance).

The temperature of the sealing must be below the temperature of the wire insulation.

To lessen the stress and abrasion of the loop wire the 90° corners shall be cut at a 45° angle or a core drilled with a minimum of 1.5” diameter (See drawings below).

16.4.3 Loop Lead Wires

The loop lead-in wire has a significant role to the functionality of the loop. Following are some important points for installing loop leads:

- The loop lead-in wire must be twisted about 7 times per ft up to the point where the wires connect to the detector.
- Leads of multiple loops should not use the same cable or conduit. If it is not possible to have separate conduits for multiple loop leads a shielded twisted-pair wire must be used for each loop.
- The lead-in length should not exceed 50 feet. Long leads can decrease the sensitivity therefore the leads should be as short as possible.

Note:

It is a must to cut the leads to the proper length. Excessive long leads looped before it is wired to the detector will decrease the loop functionality.

Do not run a loop lead through the same cut of another loop:
16.4.4 How deep should the loop wires be installed?

The deeper the wires are below the road surface the more they are protected from road surface wear and the elements. The top wire should be a minimum of 1 inch below the road surface.

Note:
Nonconductive materials such as concrete and asphalt will not influence the loop fields. Installing the loop one inch deeper (e.g. 3” depth not 2” depth) would have the same result as raising the vehicle one inch above the pavement surface.
16.4.5 Loop distance from objects:

A minimum distance of 1ft between the loop and all metal objects (steel reinforcements, sewer grill etc.) must be kept. If this is not the case the loop sensitivity can decrease significantly and a proper functioning of the loop cannot be guaranteed.

The loop and loop leads must not be installed near to any underground high voltage cables.

The distance between loops and barrier housings or barrier arms should be a minimum of 10”.

The following rule should be observed:

The longer the loop, the greater the spacing must be between the gate and the loop.

Following is a typical installation that shows how the loops should be installed. (see below).
17.0 Commissioning

17.1 Commissioning procedure

Once the barrier has been installed, the barrier boom attached and all electrical wiring work (including the installation of induction loops) have been completed, according to the instructions; the barrier can be put into operation. To avoid the risk of injury and damage arising from any unintentional barrier movements during initial operations, all persons and objects should be kept clear of the barrier.

17.2 Messages displayed during the start-up routine

The following messages are displayed during the controller start-up routine:

1. Display message:

   *** MAGNETIC***

2. Display message:

   Hard A, Boot 0002
   Hard A: Hardware version A
   Boot 0002 = Software version 0002

3. Display Message:

   MLC10-100 S24008
   MLC10-100 = Controller Type
   S240008 = Software Parameter

4. Display Message

   0009.0003 00
   0009.0003 = Software Version
   00 = Parameter Version

5. Display Message:

   MIB30 60Hz
   MIB30 = Barrier Model
   60Hz = Voltage, frequency

6. Display Message:

   See chapter 4.2 Display information
Note:
Ex factory the barrier is shipped with the reset function as “SIGNAL RESET” (see chapter 14.5 RESETTING THE BARRIER). After resetting the controller the barrier is now fully functioning.

Please use the wiring diagrams displayed in chapter 5.0 PROGRAMMING MODES for Input wiring.

17.3 Standard Configuration:
Following are the standard controller configuration ex-factory:

### 17.3.1 Parking or access control configuration:

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Default Setting</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Program Mode:</td>
<td>7</td>
<td>see chapter 5.1.7</td>
</tr>
<tr>
<td>Loop A Sensitivity:</td>
<td>5</td>
<td>see chapter 8.0 and 15.3</td>
</tr>
<tr>
<td>Loop B Sensitivity:</td>
<td>5</td>
<td>see chapter 8.0 and 15.3</td>
</tr>
<tr>
<td>Loop Mode A:</td>
<td>2</td>
<td>see chapter 9.0</td>
</tr>
<tr>
<td>Loop Mode B:</td>
<td>2 presence</td>
<td>see chapter 9.0</td>
</tr>
<tr>
<td>Safety Angle:</td>
<td>15°</td>
<td>see chapter 15.1</td>
</tr>
</tbody>
</table>

### 17.3.2 Toll road application:

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Default Setting</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Program Mode:</td>
<td>4</td>
<td>see chapter 5.1.7</td>
</tr>
<tr>
<td>Hold Open Time:</td>
<td>35sec.</td>
<td>see chapter 7.0</td>
</tr>
<tr>
<td>Loop A Sensitivity:</td>
<td>5</td>
<td>see chapter 8.0 and 15.3</td>
</tr>
<tr>
<td>Loop B Sensitivity:</td>
<td>5</td>
<td>see chapter 8.0 and 15.3</td>
</tr>
<tr>
<td>Loop Mode A:</td>
<td>0</td>
<td>see chapter 9.0</td>
</tr>
<tr>
<td>Loop Mode B:</td>
<td>0</td>
<td>see chapter 9.0</td>
</tr>
<tr>
<td>Safety Angle:</td>
<td>15°</td>
<td>see chapter 15.1</td>
</tr>
</tbody>
</table>

Note:
If your installation requires different setting please follow the instructions in the corresponding chapters.
18.0 Installation Example:

18.1 Free exit or entry configuration:
For a free entry or exit application please follow these steps:

1.0 Program Mode setting:
Mode 5, 6, 7 and 8 will work as free exit or entry application, depending on the application, set the mode accordingly. Please read chapter 5.1.5, 5.1.6, 5.1.7 and 5.1.8 for details.
Typical is Program Mode 5, which will close after the adjustable hold open timer elapses if no vehicle passed through the safety/closing loop. If this installation requires that the gate should stay up if no vehicle passes through the safety/closing loop then choose Program Mode 7.

2.0 Loop Mode A setting:
Depending on the installation requirements, set Loop Mode A to meet those specifications. Please read chapter 9.0 for further details.
Typical is Loop Mode 2, which issues a potential free maintained contact on relay K1 when a car is on the Loop.

3.0 Loop Mode B setting:
Depending on the installation requirements, set Loop Mode B to meet those specifications. Please read chapter 9.3 for further details.
For free exit or entry Loop Mode B must be set to “OPENING LOOP”. The output relay is typically set to 2 to receive a potential free maintained output on relay K2 whenever a vehicle is on the loop.
Typical is Loop Mode 2, which issues a maintained potential free contact whenever a vehicle is on the loop.

4.0 Hold Open Timer setting:
If this installation requires that the gate closes automatically after receiving an opening command without a vehicle passing through the safety closing zone, set Program Mode to 5 or 6 and set the hold-open timer according to your requirements. Please read chapter 7.0 for further details.
Typical hold open timer setting is 35sec.

Note:
After all settings are done, return the rotary switch to position 0 for normal operation.
The barrier is now in full operation mode.
18.1.1 Free entry or exit Lane Layout

The drawing below shows a typical lane layout for a fee entry or exit application.
18.1.2 Free entry or exit wiring diagram:
Below is a Free entry or exit lane wiring diagram with a device to open the barrier if configured as free exit.
18.2 Entry or exit with access control:
For a access controlled entry or exit, do the following:

1.0 Program Mode setting:
Mode 5, 6, 7 and 8 will work for this application, depending on the application, set the mode accordingly. Please read chapter 5.1.5, 5.1.6, 5.1.7 and 5.1.8 for details.
Typical is Program Mode 7, which will remain open if no vehicle passed through the safety/closing zone. If this installation requires that the gate should automatically close if no vehicle passes through the safety/closing loop, choose Program Mode 5.

2.0 Loop Mode A setting:
Depending on the installation requirements set Loop Mode A to meet those specifications. Please read chapter 9.0 for further details.
Typical is Loop Mode 2, which issued a potential free maintained contact on relay K1 when a car is on the Loop. This can be used to reset the access control equipment.

3.0 Loop Mode B setting:
In an access control application Loop B is used as presence (arming) loop. Please read chapter 9.3 for further details.
To arm the access control equipment when a vehicle is present set the Loop Mode to 2 and “PRESENCE LOOP”. This will issue a potential free maintained contact at Relay K2 whenever a vehicle is on the loop.
Typical is Loop Mode 2, which issues a maintained potential free contact at relay K2 whenever a vehicle is on the loop.

4.0 Hold Open Timer setting:
If this installation requires that the gate closes automatically after receiving an opening command without a vehicle passing through the safety closing zone, set Program Mode to 5 or 6 and set the hold-open timer according to your requirements. Please read chapter 7.0 for further details.
Typical hold open timer setting is 35sec.
18.2.1 Access Control Lane layout

The drawing below shows a typical lane layout for an access control entry or exit.

![Diagram of Access Control Lane layout](image)

- Access Control
- Loop B
- MIB Barrier
- Traffic Flow
- Max. 6'
- 3'
- 1'-6"
18.2.2 Access Control Lane wiring diagram

Below is an Access Control entry exit-wiring diagram.

[Diagram showing wiring connections and labels such as Boom Sensor, Motor, Loop A, Loop B, Safety/Closing Loop, Presence/Arming Loop, and various terminals and labels indicating connections and functions.]
18.3 Access Control one direction free in/out other direction

1.0 Program Mode setting:
Mode 6 and 8 are recommended for this application. See chapter 5.1.6, and 5.1.8 for details. If the installation requires a presence loop to arm the access control equipment an additional loop detector is required.
Typical is Program Mode 6, which will close after the adjustable hold open timer elapses if no vehicle passed through the safety/closing loop. If this installation requires that the gate should stay up if no vehicle passes through the safety/closing loop choose Program Mode 8.

2.0 Loop Mode A setting:
Loop A can only be used for the safety/closing function of the barrier. Depending on the installation requirements, set Loop Mode A to meet those specifications. Please read chapter 9.0 for further details.
Typical is Loop Mode 2, which issues a potential free maintained contact on relay K1 when a car is on the Loop.

3.0 Loop Mode B setting:
Depending on the installations requirements, set Loop Mode B to meet those specifications. Please read chapter 9.3 for further details.
For free exit or entry Loop Mode B must be set to “OPENING LOOP”. The output relay is typically set to 2 to receive a potential free maintained output on relay K2 whenever a vehicle is on the loop.
Typical is Loop Mode 2, which issues a maintained potential free contact whenever a vehicle is on the loop.

4.0 Hold Open Timer setting:
If this installation requires that the gate closes automatically after receiving an opening command without a vehicle passing through the safety closing zone, set Program Mode to 6 and set the hold-open timer according to your requirements. Please read chapter 7.0 for further details.
Typical hold open timer setting is 35sec.

Note:
After all settings are done return the rotary switch to position 0 for normal operation. The barrier is now in full operation mode.
If the installation requires a presence loop to arm the access control equipment an additional loop detector is required.
No external wiring of the opening loop is required. The MLC controller handles the opening of the barrier internally.
18.3.1 Access Control In Free Out Lane Layout

Drawing below shows a typical lane layout:

![Diagram of MIB20_30_40 Access Control in Free Out Lane Layout](image)

- **Traffic Flow**
- **Loop A**
- **Loop B**
- **Presence/Arming Loop**
- **Separate standalone loop detector**

Access Control

MIB Barrier

9'6"
18.3.2 Access Control In Free Out Lane wiring diagram

Below is an Access Control “IN” free “OUT” wiring diagram:

Program 6
18.4 Master Slave configuration

In a master slave configuration, the master barrier controls the slave barrier. All access control wiring must go to the master barrier. An additional relay (see chapter 18.4.2) is required to achieve this function. The Master can be set in Mode 5 through 8 and the Slave barrier must be set to Mode 1.

1.0 Program Mode setting:
Master Barrier:
Mode 5, 6, 7 and 8 will work for this application. Depending on the application, set the mode accordingly. Please read chapter 5.1.5, 5.1.6, 5.1.7 and 5.1.8 for details.
Typical is Program Mode 7, which will remain open if no vehicle passed through the safety/closing zone. If this installation requires that the gate should automatically close if no vehicle passes through the safety/closing loop choose Program Mode 5 or 8.
Slave Barrier:
The slave barrier will only function in Program Mode 1.

2.0 Loop Mode A setting:
Master Barrier:
Depending on the installation requirements set Loop Mode A to meet those specifications. Please read chapter 9.0 for further details.
Typical is Loop Mode 2, which issues a potential free maintained contact on relay K1 when a car is on the Loop. This can be used to reset the access control equipment.
Slave Barrier:
The Loop Mode A for the slave barrier should be 0 (= disabled). In wide lanes that require more then one loop, connect them in series to the Master MLC controller.

3.0 Loop Mode B setting:
Master Barrier:
In an access control application Loop B is used as a presence (arming) loop. Please read chapter 9.3 for further details. If no presence (arming) loop is required set Loop Mode B to 0.
To arm the access control equipment when a vehicle is present you must set the Loop Mode to “2” and “PRESENCE LOOP”. This will issue a potential free maintained contact on relay K2 whenever a vehicle is on the loop.
In a free entry or exit application, Loop B must be set to “OPENING LOOP” and the Mode depends on the application.
Typical is Loop Mode 2, which issues a maintained potential free contact at relay K2 whenever a vehicle is on the loop.
Slave Barrier:
Loop B must be set to 0 (= disabled).
4.0 Hold Open Timer setting:

Master Barrier:
If this installation requires that the gate closes automatically after receiving an opening command without a vehicle passing through the safety closing zone, set Program Mode to 5 or 6 and set the hold-open timer according your requirements. Please read chapter 7.0 for further details.
Typical hold open timer setting is 35sec.

Slave Barrier:
The Slave barrier is operated in Program Mode 1, which doesn’t support this feature, but the slave barrier will operate simultaneously with the Master barrier.
18.4.1 Master/Slave Lane layout

Following is a drawing on how to layout the lane for a Master/Slave application.
18.4.2 Master Slave wiring diagram

Below is a Master/Slave configuration-wiring diagram

Slave:
Program 1
Loop mode A & B = 0
(Disabled)

Master:
Program: 5-8

Loop Mode A: 2
Loop Mode B: as desired

A1 = Neutral Relay Coil
A2 = 24VDC Relay Coil
14 = Normally open relay contact
11 = Common Relay contact
18.5 Toll Road application:
In most Toll-road applications, a lane controller controls the gate. Therefore the gate controller must respond to all inputs without being in an automatic mode. This is achieved by using Program Mode 4. See chapter 5.1.4 for details.

1.0 Program Mode setting:
Mode 4 is recommended for this application. See chapter 5.1.4 for details.
Mode 4 will open the barrier when an input on IN1 is made and will close when an input on IN3 was made. The inputs shall be pulses of minimum 300msec..

2.0 Loop Mode A setting:
Loop A is set to Loop Mode 0 ex factory. Loop Mode 0 disables the loop detector and enables a potential free contact on relay K1 when the barrier is in the full up position. See chapter 9.2 for details.

3.0 Loop Mode B setting:
Loop B is set to Loop Mode 0 ex factory. Loop Mode 0 disables the loop detector and enables a potential free contact on relay K2 when the barrier is in the full down position. See chapter 9.3 for details.

4.0 Hold Open Timer setting:
The Hold open timer has no function in Mode 4.

Note:
After all settings are done return the rotary switch to position 0 for normal operation. The barrier is now in full operation mode.
If the installation requires a input override switch connect a normally open contact to input IN2 of the controller. This input overrides all existing inputs.
18.5.1 Toll Road lane layout

Following is a typical toll road lane layout:

Note: Loop A is not controlled by the MIB* barrier.
18.5.2 Toll Road wiring diagram

Following is a typical Toll application, wiring diagram:
19.0 MIB* barrier with boom Lock mechanism

The MIB* barriers can be operated with the boom locking mechanism. Please see Magnetic Info sheet MM5141 for details. The Info sheet is attached to this manual if a MIB* barrier with locking mechanism was purchased.

Following is a wiring diagram showing the connection of the MLC controller and the MMV1C-100 boom-locking controller:
20.0 MIB* barrier with boom lights

The MIB* barriers can be operated with the Magnetic boom lights. Please see Magnetic Info sheet MM5141 for details.
The Info sheet is attached to this manual if a MIB* barrier with boom lights was purchased.

Following is a wiring diagram showing the connection of the MLC controller and the MSS1C-100 boom-light controller:
21.0 Mechanical operation

The MIB series is based on a unique technology in which the combination of the torque-motor, springs and sinusoidal lever system assures a reliable mechanical operation. This technology together with the MLC controller and the boom-positioning sensor will operate the barrier very reliably without bouncing the arm in the end positions.

The MIB* series barrier gates are equipped with two (2) rubber end stops to absorb the shock generated by the moving gate hitting the end positions.

21.1 Spring balance

The MIB series barriers are provided with springs to balance the weight of the barrier arm. Ex-Factory the springs are set to the ordered boom length. In some cases the boom arm must be cut on side or weight has been added to the arm (Signage). Adding or lowering the weight of the arm will influence the balance of the springs.

The possible boom length depends on what type of barrier you choose; following table shows the maximum boom length

<table>
<thead>
<tr>
<th>Barrier Type</th>
<th>Maximum boom Length*</th>
</tr>
</thead>
<tbody>
<tr>
<td>MIB20</td>
<td>8ft aluminum octagonal/10ft round boom, 8 ft articulated boom</td>
</tr>
<tr>
<td>MIB30</td>
<td>12 ft octagonal aluminum boom, 12 ft articulated boom</td>
</tr>
<tr>
<td>MIB40</td>
<td>20 ft octagonal aluminum boom, 15 ft articulated boom</td>
</tr>
</tbody>
</table>

* The maximum boom lengths refer to the Magnetic Automation Corp. manufactured boom models MSB5N-025 (8ft), MSB5N-030 (10ft), MSB5N-035 (12 ft), MSB5N-045 (15ft), MSB5N-060 (20 ft), MSB5K-025 (8ft articulated), MSB5K-030 (10ft articulated), MSB5K-035 (12ft articulated) and MSB5K-045 (15ft articulated).

In order to balance the arm to the springs follow these steps:

1. Remove the top housing cover
2. The springs are located on the back of the drive unit (see drawing below)
3. Each boom length requires different spring tension and therefore different quantities of springs (see table below)

<table>
<thead>
<tr>
<th>Boom Length</th>
<th>MIB20</th>
<th>MIB30</th>
<th>MIB40</th>
</tr>
</thead>
<tbody>
<tr>
<td>MSB5N -025 8FT ALUMINUM OCTAGONAL</td>
<td>2</td>
<td>2</td>
<td></td>
</tr>
<tr>
<td>MSB5N -030 10FT ALUMINUM OCTAGONAL</td>
<td>N/A</td>
<td>3</td>
<td></td>
</tr>
<tr>
<td>MSB5N -035 12FT ALUMINUM OCTAGONAL</td>
<td>N/A</td>
<td>4</td>
<td>2 (STRONG SPRINGS, YELLOW MARK)*</td>
</tr>
<tr>
<td>MSB5N -045 15FT ALUMINUM OCTAGONAL</td>
<td>N/A</td>
<td>N/A</td>
<td>4 (STRONG SPRINGS, YELLOW MARK)*</td>
</tr>
<tr>
<td>MSB5N -060 20FT ALUMINUM OCTAGONAL</td>
<td>N/A</td>
<td>N/A</td>
<td>6 (STRONG SPRINGS, YELLOW MARK)*</td>
</tr>
<tr>
<td>MSB4B-030 10FT ROUND ALUMINUM BOOM</td>
<td>3</td>
<td>3</td>
<td>N/A</td>
</tr>
</tbody>
</table>

* The MIB40 uses a springs that have a higher tension then the MIB20&30’s. The MIB40 springs are marked with yellow paint on each of the ends.

The above table does not ably to articulated barrier arms (Part# MSB5K-025/030/035/045). All Magnetic Automation Corp. articulated barrier arms are custom made to specifications provided by the client. The differences in the lane clearance height influence the weight of the barrier arm and therefore each articulated arm must be adjusted to the individual barrier.

4. In order to balance the springs you have to move the barrier arm to a 45° angle. The gate arm is balanced when it stays at this position without any electrical power applied to the gate.

5. If the arm moves down, the springs are too weak; if it moves up the springs are too tight.

6. To adjust the springs to the correct tension, remove the plastic clips that hold the adjustment screws in place. Turn the adjustment screws to raise or lower the springs (raise= higher tension, low= lower tension) until the arm is balanced.

7. After balancing the arm replace the plastic spring clips.

8. Replace the housing lid and turn the power on.

9. Now the controller brake needs to be set to the new settings. Follow instructions in chapter 22.1 to re-adjust the gate arm brake settings.
21.2 Barrier arm support

Barrier arm length exceeding 14ft require a support of the boom arm in the lower end position to cushion the arm when it travels in the down position. Magnetic Automation Corp. offers two options of barrier arm supports:

21.2.1 Pendulum support

The pendulum support (Part# 1043.0138) is mounted to the barrier arm via two Allen head bolts (see drawing below).

Note:
Depending on roadway conditions the pendulum might have to be lengthened or shortened. To change the length of the support loosen the three set screws located on the center ring of the rod and turn the bottom cylinder clockwise to lengthen or counter clockwise to shorten the support. When the gate arm is in the down position, the distance between the rubber stop and the beginning of the tube should be at about 14". This results in a good damping effect and prevents the rubber from freezing to the tube in cold climate. After the proper length has been adjusted tighten the three set screws again.

21.2.2 Support Post

The support post (Part# MAP5N-110) is mounted to the ground on the end of the gate arm. The arm drops into the cradle when the barrier is in the down position (see drawing)
Note:
The height of the support post can be adjusted to compensate differences in height between the barrier and the support post foundation.
22.0 Troubleshooting

22.1 Adjusting the boom position sensor

In case the barrier lost its current position or if a new MLC* controller must be installed in an existing barrier the display message “ADJUST SENSOR!” will appear on the display.

If this is the case please follow these steps:

1. Display message:

   ![ADJUST SENSOR !](image)

2. Make sure the gate arm is in the up position.

3. To bring the controller to the sensor adjust mode, turn the rotary switch to position 1, then press and hold the black button while returning the rotary switch to position 0.

   Display Message:

   ![SENSOR xxx](image)

   XXXX = The displayed value should be between 555 and 585. Depending what gate type is installed. See Table below for values.

<table>
<thead>
<tr>
<th>Gate Type</th>
<th>Sensor Value Up</th>
<th>Sensor Value down</th>
</tr>
</thead>
<tbody>
<tr>
<td>MIB20</td>
<td>0555 - 0580</td>
<td>0120 - 0135</td>
</tr>
<tr>
<td>MIB30</td>
<td>0555 - 0580</td>
<td>0120 – 0135</td>
</tr>
<tr>
<td>MIB40</td>
<td>0555 - 0580</td>
<td>0120 – 0135</td>
</tr>
</tbody>
</table>

4. Push the black and the white button simultaneously. The display shows the MIB20 barrier with 50Hz motor winding first.

   Display Message:

   ![MIB20 50 Hz](image)

   MIB20 = Gate type
   50 Hz = Line Voltage Frequency
5.0 To select the installed gate model press the back button until you reach the correct model on the display. If you are not certain which gate is installed, close the fold down controller board. The gate type is written on the serial number label on the left upper side of the closed controller mounting board.

<table>
<thead>
<tr>
<th>Display message</th>
<th>Gate Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>MIB20 50 Hz</td>
<td>MIB20*-A100 (230VAC, 50Hz)</td>
</tr>
<tr>
<td>MIB20 60 Hz</td>
<td>MIB20*-C100 (115VAC, 60Hz)</td>
</tr>
<tr>
<td>MIB30 50 Hz</td>
<td>MIB30*-A100 (230VAC, 50Hz)</td>
</tr>
<tr>
<td>MIB30 60 Hz</td>
<td>MIB30*-C100 (115VAC, 60Hz)</td>
</tr>
<tr>
<td>MIB40 50 Hz</td>
<td>MIB40*-A100 (230VAC, 50Hz)</td>
</tr>
<tr>
<td>MIB40 60 Hz</td>
<td>MIB40*-C100 (115VAC, 60Hz)</td>
</tr>
</tbody>
</table>

6.0 When the correct gate type is displayed press the white button to confirm the setting.

Display Message:

Close barrier  

7.0 Pressing the black and the white button simultaneously will close the barrier.

Attention: The gate arm will now close with full torque. Make sure nothing is in its way. If the boom length is longer than 14 ft please make sure the pendulum support is in place.

Display Message:

Please wait XXXX

8.0 The controller is now testing if the down position is within the preset limits (see table on previous page). When finding the correct position, the following is displayed.

Display Message:

Open barrier  

9.0 When pressing the black and the white button simultaneously the barrier will start to open.

Attention: The gate arm will now open with full torque. Make sure nothing is in its way. If the boom length is longer than 14 ft please make sure the pendulum support is in place.

Display Message:

Please wait XXXX
10.0 The controller is now testing if the up position is within the preset limits (see table). When finding the correct position the following is displayed.

Display Message:

Sensor Adjusted

11.0 The position sensor is now adjusted. Based on this adjustment the controller must now find the optimum brake points for the gate type and the boom length. To do so press the black and the white button simultaneously.

Display Message:

Close barrier

12.0 When pressing the black and the white button simultaneously the barrier will start the brake adjustment procedure. During this adjustment the gate will open and close until it finds the optimal brake points. This procedure may take up to 5 minutes depending on gate type and boom length.

Attention: The gate arm will now cycle up and down. Make sure nothing is in its way. If the boom length is longer than 14 ft please make sure the pendulum support is in place.

13.0 After the gate arm found the optimum brake points following is displayed.

Display Message:

Brake Adjusted

14.0 The controller has now found the optimum brake points for this barrier. To return to the normal operation turn the rotary switch to position 1 and then back to 0.

15.0 After this process the controller settings must now be set to suit the requirements for this installation: Program Mode (see chapter 5.0), Loop Mode (see chapter 9.0).

16.0 After the settings have been done, return the rotary switch to position 0 for normal operation.
22.2 Boom Sensor out of adjustment

If the procedure explained in chapter 22.1 does not solve the problem or if the display keeps flashing when the barrier is trying to find its end position, the position sensor is out of adjustment. Following table shows the correct position value for the gates

<table>
<thead>
<tr>
<th>Gate Type</th>
<th>Sensor Value Up</th>
<th>Sensor Value down</th>
</tr>
</thead>
<tbody>
<tr>
<td>MIB20</td>
<td>0555 - 0580</td>
<td>0120 - 0135</td>
</tr>
<tr>
<td>MIB30</td>
<td>0555 - 0580</td>
<td>0120 – 0135</td>
</tr>
<tr>
<td>MIB40</td>
<td>0555 - 0580</td>
<td>0120 – 0135</td>
</tr>
</tbody>
</table>

To re-position the sensor to the correct position please follow these steps:

1.0 Move gate to the complete up position
2.0 Turn rotary switch to position 1, then press and hold both the black and the white button while returning the rotary switch to position 0.

Display Message:

```
SENSOR xxxx
```

`xxxx` = The displayed value should be between 555 and 585. Depending what gate type is installed.

4.0 The sensor must now be physically adjusted. The sensor is located on the opposite side of the drive shaft (see picture).

5.0 The sensor is attached to the drive shaft via a 5mm set screw. Use a 2.5mm hex key (Allen Wrench) to loosen the set-screw (do not remove it completely).

6.0 After loosening the stud screw you are now able to pull the sensor out.
7.0 While closely monitoring the numbers on the controller display, turn the shaft in the
directed direction. When the correct value is displayed (see table on previous page)
return the sensor back into drive shaft and tighten the setscrew.

8.0 Recheck that the sensor value on the controller hasn’t changed after tightening the
setscrew. If the sensor value is within the limits press the black and the white button
simultaneously to start the self-adjusting process.
The display shows the MIB20 barrier with 50Hz motor winding first.

Display Message:

```
MIB20  50 Hz
```

9.0 To select the installed gate type press the black button until you reach the correct
gate type on the display. If you are not certain which gate is installed close the fold down
ccontroller board. The gate type is written on the serial number label on the left upper
side of the closed controller mounting board.

10.0 When the correct gate type is displayed press the white button to confirm the
setting.
Display Message:

```
Close barrier  ?
```

11.0 Pressing the black and the white button simultaneously the barrier will start to
close.
Attention: The gate arm will now close with full torque. Make sure nothing is in its way.
If the boom length is longer than 14 ft please make sure the pendulum support is in
place.

Display Message:

```
Please wait XXXX
```

12.0 The controller is now testing if the down position is within the preset limits (see
table). When finding the correct position, the following is displayed.
Display Message:

```
Open barrier  ?
```

```
MIB20 = Gate type
50 Hz = Line Voltage Frequency
XXXX = The displayed value
should be between 120 and 135,
depending what gate type is
installed. See Table above for
values.
```
13.0 When pressing the black and the white button simultaneously the barrier will start to open.

Attention: The gate arm will now open with full torque. Make sure nothing is in its way. If the boom length is longer than 14 ft please make sure the pendulum support is in place.

Display Message:

Please wait XXXX

XXXX = The displayed value should be between 555 and 580, depending what gate type is installed. See Table above for values.

14.0 The controller is now testing if the up position is within the preset limits (see table). When finding the correct position the following is displayed.

Display Message:

Sensor Adjusted

15.0 The position sensor is now adjusted. Based on this adjustment the controller must now find the optimum brake points for the gate type and the boom length. To do so press the black and the white button simultaneously.

Display Message:

Close barrier ?

16.0 When pressing the black and the white button simultaneously the barrier will start the brake adjustment procedure. During this adjustment the gate will open and close until it finds the optimal brake points. This procedure may take up to 5 minutes depending on gate type and boom length.

Attention: The gate arm will now cycle up and down. Make sure nothing is in its way. If the boom length is longer than 14 ft please make sure the pendulum support is in place.

17.0 After the gate arm finds the optimum brake points following message is displayed.

Display Message:

Break Adjusted
18.0 The controller has now found the optimum brake points for this barrier. To return to the normal operation turn the rotary switch to position 1 and return it to 0 for normal operating mode.

22.3 Loop Detector error
The MLC controller is equipped with a loop detector diagnostic feature. If there is a loop error it will be displayed on the controller display.

Following are the detector status display:

- A rectangular box means that this loop detector is activated and the loop is connected and read properly.
- A rectangular box with a cross means that this loop detector is activated and a vehicle is present on the loop.
- An exclamation mark means that the loop is not activated.
Note:
If any of the above error messages appear please make sure that

a. The loop is connected at all  
b. The Loop is connected to the proper terminals  
c. The Loop has the correct turns and is laid out properly  
d. The loop has the correct insulation resistance to earth.  
e. That you disabled the loop detectors that are not used.

Please see chapter 16.0 for more details. If you require more detailed information regarding loop installation and Magnetic Automation’s loop detectors please ask for the newest INDUCTIVE LOOP DETECTOR MANUAL.

22.4 Gate does not close
There can be different reasons for why the barrier isn’t closing. Following are a few examples:

1. Barrier does not go all the way down:
Reason:
A: Make sure that the barrier arm is attached to the gate. The MIB barrier arms are balanced with springs, without the weight of the arm the motor is not able to close the barrier.

B: The spring tension is too strong. Ex-Factory the gate is adjusted for the ordered boom length. If for any reason the arm is shorter then adjusted ex factory the springs need to be readjusted to balance the new weight of the shorter boom. See chapter 22.6 for more details.

2. Barrier does not react to any closing inputs
Reason:
A: Make sure that input IN5 is made. IN5 is the safety input for external safety devices other then induction loops connected on Loop A. If Loop A is activated, input IN5 must be made (jumper wire terminal 32-33 delivered ex-factory). If an external safety device is
used (for example: Photo Beam) the normally closed contact of this device must be
c connected to this terminal. If Input IN5 is not made the gate will not close.

**B:** Make sure that safety device, externally connected on IN5 (if used) or the internal safety
loop A is not triggered. The barrier won’t close if the safety device is activated.

**C:** If the gate should close by passing through the safety device please check if the safety
device is actually being triggered when a vehicle drives through the safety zone. If Loop A
is used for safety/closing check if a cross appears in the square on the Loop A status
display when the vehicle is on the loop. If an external safety/closing device is used make
sure the status display of IN5 displays “0” when the vehicle is on the safety zone and
returns to “1” when the vehicle has left. The gate should then close.

**D:** If using the safety/closing loop/device to close the gate, make sure the Program mode
is set to 5, 6, 7 or 8 (see chapter 5.0 for more details).

**C:** If you are using inputs to close the barrier make sure you connected it to the correct
 terminals in respect to the program modes (see chapter 5.0 for more details).

**Note:**
In any case; if the barrier does not open or close try the provided gate
UP/NORMAL/DOWN switch first to determine if the problem comes from the gate or the
peripheral equipment.

### 22.5 Gate does not open

There can be several reasons for why the barrier isn’t opening. Following are a few
examples:

**A:** The barrier arm is too heavy. The spring tension is too weak. Ex-Factory the gate is
adjusted for the ordered boom length. If for any reason the arm is longer or additional
weight was added to it (for example: Stop signs) the springs have to be readjusted to
balance the boom arm. The motor is not strong enough to lift the arm if the springs are
not balanced with the arm. See chapter 22.6 for more details.

**B:** Make sure the barrier open contact is connected to the correct terminal. See chapter
5.0 for details.

**C:** Make sure that IN3 is not made. This contact has higher priority then IN1. If using IN1
to open the gate IN3 must be off.

**Note:**
In any case, if the barrier does not open or close try the provided gate
UP/NORMAL/DOWN switch first to determine if the problem comes from the gate or the
peripheral equipment.
22.6 How to change from right-handed gate to left-handed?

On which side of the housing the boom is positioned and in what relation to the road the housing is positioned determines if the gate is right or left handed. Please see drawing below for further details.

Ex-factory we ship the barrier as ordered, either right or left-handed. If during installation the barrier has to be changed from right to left handed or vise versa please follow the steps below:

1. Move the barrier to the up position.
2. Turn the electrical power off.
3. Remove the gate arm from the flange.
4. Loosen up or remove the springs (before loosing up the springs please make sure you remember how tight they were when putting them back on).
5. Loosen (do not completely remove) the two Allen bolts that clamp the shaft lever to the shaft.
6. Remove the retainer ring that’s holding the shaft in place opposite from the flange.
7. Take off the distance bushings.
8. You can now pull the shaft out of the drive unit frame. Sometimes it is necessary to use a screwdriver or a similar tool to wedge the shaft lever when pulling the shaft out.
9. Slide the shaft into the opposite side all the way through.
10. Replace the distance bushings and the retainer ring.
11. Level the boom flange parallel to the gate housing and retighten the two Allen head bolts.
12. Replace or re-tension the springs to the position in which they originally were.
13. Replace the barrier arm.
14. Turn the power back on.
15. Close the barrier
16. Check the horizontal position of the gate arm to the driveway.
17. If the gate arm is not parallel to the driveway open up the two Allen head bolts that secure the shaft lever to the shaft and adjust the arm position.
18. When the arm is parallel to the driveway re-tighten the two Allen head bolts.
23.0 Technical Data

23.1 MAGSTOP Barriers

<table>
<thead>
<tr>
<th></th>
<th>MIB20</th>
<th>MIB30</th>
<th>MIB40</th>
</tr>
</thead>
<tbody>
<tr>
<td>Max. Boom length</td>
<td>8FT octagonal/10ft round</td>
<td>12FT octagonal</td>
<td>20 FT octagonal</td>
</tr>
<tr>
<td>Opening/closing time</td>
<td>0.9 sec</td>
<td>1.4 sec</td>
<td>4.0 sec</td>
</tr>
<tr>
<td>Power consumption</td>
<td>240 W</td>
<td>120 W</td>
<td>120 W</td>
</tr>
<tr>
<td>Housing</td>
<td>Zinc-plated sheet steel color powder coated</td>
<td>Zinc-plated sheet steel color powder coated</td>
<td>Zinc-plated sheet steel color powder coated</td>
</tr>
<tr>
<td>Housing dimensions</td>
<td>14” x 14” x 42”</td>
<td>14” x 14’’ x 42”</td>
<td>14” x 14’’ x 42”</td>
</tr>
<tr>
<td>Foundation base frame</td>
<td>Stainless steel</td>
<td>Stainless steel</td>
<td>Stainless steel</td>
</tr>
<tr>
<td>Weight (without arm)</td>
<td>145 lbs.</td>
<td>145 lbs.</td>
<td>145 lbs.</td>
</tr>
<tr>
<td>Operating temp. Range (Ambient)</td>
<td>-22°F TO +140°F</td>
<td>-22°F TO +140°F</td>
<td>-22°F TO +140°F</td>
</tr>
<tr>
<td>Drive Unit</td>
<td>Torque motor</td>
<td>Torque motor</td>
<td>Torque motor</td>
</tr>
</tbody>
</table>

23.2 Controller

<table>
<thead>
<tr>
<th></th>
<th>Unit</th>
<th>MLC10</th>
<th>MLC11*</th>
</tr>
</thead>
<tbody>
<tr>
<td>Voltage (+/- 10%)</td>
<td>Volt</td>
<td>100-240</td>
<td>100-240</td>
</tr>
<tr>
<td>Frequency</td>
<td>Hertz</td>
<td>50 - 60</td>
<td>50 - 60</td>
</tr>
<tr>
<td>Max. power consumption</td>
<td>Watt</td>
<td>20</td>
<td>20</td>
</tr>
<tr>
<td>Fuse</td>
<td></td>
<td>F4AH</td>
<td>F4AH</td>
</tr>
<tr>
<td>Control Voltage</td>
<td></td>
<td>24 V DC / max. 300 mA</td>
<td>24 V DC / max. 300 mA*</td>
</tr>
<tr>
<td>No. of inputs</td>
<td>5</td>
<td>5</td>
<td>5</td>
</tr>
<tr>
<td>No of zero-potential changeover relays</td>
<td>max.250V AC/3A 2</td>
<td>2</td>
<td>2</td>
</tr>
<tr>
<td>No. of open collector outputs</td>
<td>max.50mA/24V DC</td>
<td>2</td>
<td>2</td>
</tr>
</tbody>
</table>
## Operation Instructions

<table>
<thead>
<tr>
<th>Unit</th>
<th>MLC10</th>
<th>MLC11*</th>
</tr>
</thead>
<tbody>
<tr>
<td>Display Characters</td>
<td>16</td>
<td>16</td>
</tr>
<tr>
<td>Choice of languages</td>
<td>D-GB-F-E</td>
<td>D-GB-F-E</td>
</tr>
<tr>
<td>No. of loop detectors</td>
<td>2</td>
<td>2</td>
</tr>
<tr>
<td>Induction range</td>
<td>μH</td>
<td>70 - 500</td>
</tr>
<tr>
<td>No of sensitivity settings</td>
<td>10</td>
<td>10</td>
</tr>
<tr>
<td>Sensitivity range</td>
<td>%</td>
<td>0.01-2</td>
</tr>
<tr>
<td>Protection Class</td>
<td>IP</td>
<td>20</td>
</tr>
<tr>
<td>Weight</td>
<td>Lbs</td>
<td>2</td>
</tr>
<tr>
<td>Dimensions</td>
<td>Inch (L x W x H)</td>
<td>7.87”x2.95”x4.64”</td>
</tr>
</tbody>
</table>

*The MIB 20 barrier shall only be used in conjunction with the MLC 11 (external heat sink). The MLC11 controller requires that the heat sink screw be installed through the fold down steel mounting plate.
24. Maintenance

The MIB20/30/40 series barrier gates are designed for a long lifetime with only a minimum of maintenance required. To guarantee the greatest available equipment uptime and maximize the lifetime of the MIB20/30/40 series barriers please follow the prescribed maintenance schedules.

Use the Maintenance Service Record, located on page 98, to keep track of your maintenance and upkeep activities on the MIB series barrier models.

24.1 Changing the Rubber End Stop
The MIB* series barrier gates are equipped with two (2) rubber end stops to absorb the shock generated by the moving gate hitting the end positions. Those rubber end stops need to be replaced once per year or after one million cycles whatever comes first.

24.2 Checking the Exterior of Cabinet
Inspect the housing for vehicular damage every six months.

24.3 Check the barrier arm and the attachment kit
Inspect the barrier arm for physical damage and check if the barrier arm attachment kit is used properly and all parts are in place and tight. Perform this inspection every six months.

24.4 Checking the Loop Detectors and Loop Wires
Check the frequencies of the loops every six months. The loop wires should be replaced approximately every four years or as needed. Check the loop sealant every year for cracks or peeling. Replace if needed.

24.5 Check safety signage
Inspect for proper attachment of all safety related signage such as Gate Cabinet and barrier arm safety sticker.
### 24.5 Maintenance Service Record

**Maintenance Schedule and Service Record**

<table>
<thead>
<tr>
<th>Gate Model</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Gate Serial Number</td>
<td></td>
</tr>
<tr>
<td>Date Of Installation</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Minimum</td>
</tr>
<tr>
<td></td>
<td>Date</td>
</tr>
<tr>
<td></td>
<td>Date</td>
</tr>
<tr>
<td></td>
<td>Date</td>
</tr>
<tr>
<td></td>
<td>Date</td>
</tr>
<tr>
<td>Replace Rubber End Stop</td>
<td>Every year</td>
</tr>
<tr>
<td>Inspect Cabinet</td>
<td>Every 6 months</td>
</tr>
<tr>
<td>Inspect barrier arm</td>
<td>Every 6 months</td>
</tr>
<tr>
<td>Check Loop Frequencies</td>
<td>Every 6 months</td>
</tr>
<tr>
<td>Check Loop Sealant</td>
<td>Every year</td>
</tr>
<tr>
<td>Check/replace Loop wires</td>
<td>Every 4 years</td>
</tr>
<tr>
<td>Replace Gate safety sticker</td>
<td>Every 4 years</td>
</tr>
</tbody>
</table>
25. Spare parts

MIB20 / 30 / 40

1018,5001
Motor lever

2047,5000
Upper spring bracket

1071,5004
Lower spring bracket

3004,0001
Rubber
End stop

1031,0321
Potentiometer

1014,0029
Flange-shaft

Housing base
2061.0070 (Orange)
2061.5027 (White)
2061.5042 (Yellow)
2061.5041 (Red)

Housing door
2043.0152 (Orange)
2043.5082 (White)
2043.5097 (Yellow)
2061.5096 (Red)

Housing Lid
2029.0023 (Orange)
2029.5031 (White)
2043.5040 (Yellow)
2061.5039 (Red)
3468,0028
#18 Lock for hood and door

3004,0005
Hood bumper

3224,0020
Door Gasket

3466,0019
#18 Key

3514,5000
Wave-ring
For hood plug

3502,5001
Distance Ring
For hood plug

2036,0021
Spring, strong
For MIB40 only

2036,0022
Spring weak
For MIB20/30
1006,0029  16µf Capacitor
1006,0030  20µf Capacitor
1031,0180  Boom attachment kit
1031,0253  Boom Flange
1031,5055  Flange-set complete
1031,5052  
Octagonal swing away flange-set

1031,0282  
Round boom swing away flange set

1031,5037  
Wood boom flange set
Notes: